

# Incremental encoder + DC tachogenerator

## ITD 3 + KTD 3-... A 4



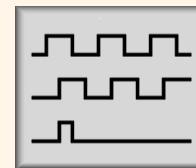
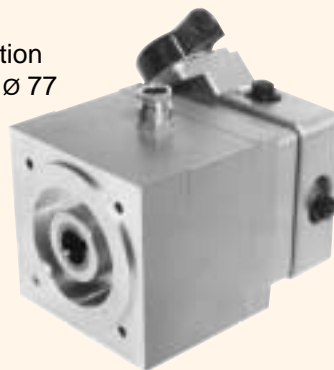
### Qualities:

- Number of pulses, up to 1024 pulses per revolution
- Centering seat  $\varnothing 70$ , mounting punching circle  $\varnothing 77$
- TTL- or HTL-output signals
- Connector outlet optional

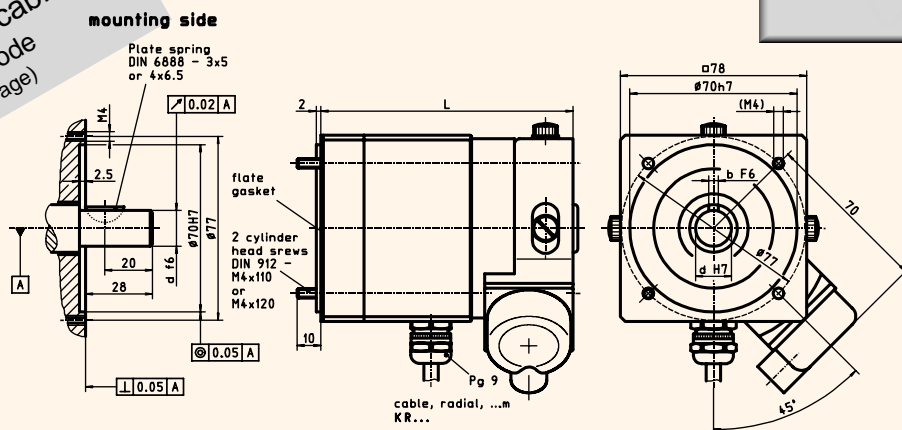
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- High reaction rate
- Small percent ripple

**commencing in July '99**  
 New connection cable  
 ⇒ new color code  
 (see reverse page)



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Type	VDC	L
ITD 3 + KTD 3-1 A 4	10	105.5
ITD 3 + KTD 3-2 A 4	20	105.5
ITD 3 + KTD 3-3 A 4	30	105.5
ITD 3 + KTD 3-4 A 4	40	115.5
ITD 3 + KTD 3-6 A 4	60	115.5

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**drawing-no.: 015 - 2**

### Mechanical data:

Housing		light-alloy metal, unpainted; steel, zined
Design style	<b>A 4</b>	A 4
Protective class	<b>IP54</b>	IP 54
Construction principle (incremental encoder)		GaAs-diode with slotdisc
max. revolution (mechanical)	$n_{max}$	$\leq 6000$ rpm (observe frequency limit)
Starting torque	at 20 ° C	$\leq 3$ Ncm
Vibration	50... 2000 Hz	$\leq 100$ m/s <sup>2</sup>
Shock	11 ms	$\leq 1000$ m/s <sup>2</sup>
Shaft diameter	d	15 mm (standard) (10 to 16 mm possible)

### Electrical data ITD:

• Number of pulses	Z	<b>XXXX</b>	1 up to 1024 pulses per revolution (standard values at request)
• Execution of electronic	TTL	<b>T</b>	TTL-output signals supply voltage: $U_B = 5$ VDC $\pm 5\%$ (poling error safe) output amplitude: $U_{LOW} \leq 0.5$ V $U_{HIGH} \geq 2.5$ V HTL-output signals supply voltage: $U_B = 8 - 30$ VDC (poling safe error) output amplitude: $U_{LOW} \leq 1.5$ V $U_{HIGH} \geq U_B - 3$ V 2 square-wave pulse trains phase shifted by 90° ( $\pm 10^\circ$ ) electr. + inverting puls : pause = 1 : 1 $\geq 15$ V/ $\mu$ s
	HTL	<b>H</b>	line driver-output stage push pull-output stage (shortening proof) ( refer to output signals-diagram ) $\pm 10\%$ at 30 kHz
• Output signals	A,B + Inv.	<b>BI</b>	
Pulse ratio			
Flank steepness			
Frequency limit	$f_G$	<b>TTL</b>	60 kHz
Output load current	$I_{Load}$	<b>TTL</b>	$\leq 70$ mA
		<b>HTL</b>	60 kHz
		<b>HTL</b>	$\leq 70$ mA

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## ITD 3 + KTD 3-... A 4



Input current (without load) $I_{max}$	≤ 150 mA	
Permissible cable length	≤ 100 m	( Thalheim-cable )
• Type of connection	<b>KR1</b>	cable, radial, 1.0 m ( standard length )
• Operating temperature range	<b>S</b>	- 20 °C to + 70 °C

### Electrical data **KTD**:

### referenced at 1000 rpm

Polarity	dependent on rotation direction
Number of pole pair	2 = 4-poles
Number of grooves, segments	29
Grooves frequency	$f_N = \frac{29}{30} \cdot n$
Reversing error	≤ ± 0.1 %
Residual ripple	≤ 0.4 %
Residual ripple frequency	200 Hz
Linearity error	≤ 0.15 %
Regulation range lower limit $n_R$	0 rpm
Temperature drift ( -10 °C to + 100 °C )	± 0.1 % / 10 K ( compensated )

Type of connection	terminal box, 2-poles
Isolation class	B
Carbon brushes	4 pieces AG 3 x 4 x 12
Carbon brushes life	approx. 20000 hours of operation
Maintenance	after 10000 hours in service

Type	Rated voltage [ VDC ]	Rated current [ mA ]	max. current [ mA ]	Armature resistance [ Ohm ]	Upper speed limit [ rpm ]	Weight [ g ]
ITD 3 + KTD 3-1	10	10	100	45	6000	1690
ITD 3 + KTD 3-2	20	10	80	170	6000	1690
ITD 3 + KTD 3-3	30	10	80	170	6000	1690
ITD 3 + KTD 3-4	40	10	80	220	4000	1930
ITD 3 + KTD 3-6	60	30	80	220	3000	1930

### Options:

- Execution of electronic **R** TTL-output signals *line driver-output stage*  
supply voltage:  $U_B = 8 - 30$  VDC ( poling error safe )
- Output signals **NI** 2 square-wave pulse trains + zero pulse, 90° electr. length + inv.
- Type of connection *ITD* **B1BR...** build-in type 1, bush contacts, radial, ...-poles
- Operating temperature range **E** - 20 °C to + 100 °C
- Enhanced protective class *A, B, N + Inv.* connector

### Accessories:

- Coupling, for version **B1B...** **K1SG...** coupling type 1, pin contacts, straight, ...-poles

### Connection table:

wire color	wire color	signals
<b>New commencing in July '99</b>	<b>Old valid until June '99</b>	
brown	green	= A
green	brown	= A inverted
grey	grey	= B
pink	black	= B inverted
red	pink	= N
black	white	= N inverted
brown 0.5 mm <sup>2</sup>	red	= + $U_B$
white 0.5 mm <sup>2</sup>	blue	= 0 V
blue		= + $U_{sensor}$
white		= 0 V <sub>sensor</sub>
transparent		= shilding/housing
	yellow	= housing
	transparent	= shilding

### Output signal diagram:

